
python-snap7 Documentation

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CHAPTER 1

Introduction

python-snap7 is a Python wrapper for the [Snap7 library](#). Snap7 is an open source, 32/64 bit, multi-platform Ethernet communication suite for interfacing natively with Siemens S7 PLCs.

Python-snap7 is developer for snap7 1.1.0 and Python2.7. It is tested on Windows (8.1 64 bit) and Linux, but it may work on other operating systems. Python 2.6 and Python 3+ may work, but are not fully tested yet.

The project development is centralized on [github](#).

CHAPTER 2

Installation

here you can find out how to install python-snap7 on your system.

Snap7

To use python-snap7 you need to have the snap7 library installed.

Ubuntu

If you are using Ubuntu you can use the Ubuntu packages from our [launchpad PPA](#). To install:

```
$ sudo add-apt-repository ppa:gijzelaar/snap7
$ sudo apt-get update
$ sudo apt-get install libsnap7 libsnap7-dev
```

Windows

Download the zip file from the [sourceforce page](#). Unzip the zip file, and copy* releaseWindows<Win64/Win32>snap7.dll* somewhere in you system PATH, for example *C:WINDOWSsystem32*. Alternatively you can copy the file somewhere on your file system and adjust the system PATH.

Compile from source

If you are not using Ubuntu or if you want to have more control you can download the latest source from [the sourceforce page](#) and do a manual compile. Download the file and run:

```
$ p7zip -d snap7-full-1.0.0.7z # requires the p7 program
$ cd build/<platform>        # where platform is unix or windows
$ make -f <arch>.mk           # where arch is your architecture, for example x86_64_
↪ linux
```

For more information about or help with compilation please check out the documentation on the [snap7 website](#).

snap7-python

python-snap7 is available on [PyPI](#). You can install it by using pip:

```
$ pip install python-snap7
```

You can also install it from the git repository or from a source tarball:

```
$ python ./setup.py install
```

Github

We develop python-snap7 on [github](#). If you have any problems with python-snap7 please raise an issue in the [issue tracker](#). Even better is if you have a solution to problem! In that case you can make our live easier by following these steps:

- fork our repository on github
- Add a tests that will fail because of the problem
- Fix the problem
- Run the test suite again
- Commit to your repository
- Issue a github pullrequest.

Also we try to be as much pep8 compatible as possible, where possible and reasonable.

Test suite

python-snap7 comes with a test suite with 100% coverage. This test suite verifies that the code actually works and makes development much easier. To run all tests please run from the source:

```
$ ./run_tests.sh
```

Note that some tests require to run as root, since snap7 needs to bind on a privileged TCP port.

If the test complain about missing Python modules make sure the source directory is in your PYTHONPATH environment variable, or the python-snap7 module is installed.

Credits

python-snap7 is created by Gijs Molenaar and Stephan Preeker.

Special thanks to go to Davide Nardella for creating snap7, Thomas Hergenbahn for his libnodave and Thomas W for his S7comm wireshark plugin.

Snap7 client used for connection to a siemens7 server.

class snap7.client.**Client**

A snap7 client

ab_read (*start, size*)

This is a lean function of Cli_ReadArea() to read PLC process outputs.

ab_write (*start, data*)

This is a lean function of Cli_WriteArea() to write PLC process outputs

as_ab_read (*start, size*)

This is the asynchronous counterpart of client.ab_read().

as_ab_write (*start, data*)

This is the asynchronous counterpart of Cli_ABWrite.

as_ct_read ()

as_ct_write ()

as_db_fill ()

as_db_get (*db_number*)

This is the asynchronous counterpart of Cli_DBGet.

as_db_read (*db_number, start, size*)

This is the asynchronous counterpart of Cli_DBRead.

Returns user buffer.

as_db_write (*db_number, start, data*)

copy_ram_to_rom ()

create ()

create a SNAP7 client.

db_get (*db_number*)

Uploads a DB from AG.

db_read (*db_number, start, size*)

This is a lean function of Cli_ReadArea() to read PLC DB.

Returns user buffer.

destroy ()

destroy a client.

full_upload (*_type, block_num*)

Uploads a full block body from AG. The whole block (including header and footer) is copied into the user buffer.

Parameters **block_num** – Number of Block

get_block_info (*blocktype, db_number*)

Returns the block information for the specified block.

get_connected ()

Returns the connection status

Returns a boolean that indicates if connected.

get_cpu_info ()

Retrieves CPU info from client

get_cpu_state ()

Retrieves CPU state from client

get_param (*number*)

Reads an internal Client object parameter.

get_pdu_length ()

Returns info about the PDU length.

list_blocks ()

Returns the AG blocks amount divided by type.

Returns a snap7.types.BlocksList object.

list_blocks_of_type (*blocktype, size*)

This function returns the AG list of a specified block type.

plc_cold_start ()

cold starts a client

plc_hot_start ()

hot starts a client

plc_stop ()

stops a client

read_area (*area, dbnumber, start, size*)

This is the main function to read data from a PLC. With it you can read DB, Inputs, Outputs, Merkers, Timers and Counters.

Parameters

- **dbnumber** – The DB number, only used when area= S7AreaDB
- **start** – offset to start writing
- **size** – number of units to read

read_multi_vars (*items*)

This function read multiple variables from the PLC.

Parameters **items** – list of S7DataItem objects

Returns a tuple with the return code and a list of data items

set_connection_params (*address, local_tsap, remote_tsap*)

Sets internally (IP, LocalTSAP, RemoteTSAP) Coordinates. This function must be called just before Cli_Connect().

Parameters

- **address** – PLC/Equipment IPV4 Address, for example “192.168.1.12”
- **local_tsap** – Local TSAP (PC TSAP)
- **remote_tsap** – Remote TSAP (PLC TSAP)

set_connection_type (*connection_type*)

Sets the connection resource type, i.e the way in which the Clients connects to a PLC.

Parameters **connection_type** – 1 for PG, 2 for OP, 3 to 10 for S7 Basic

upload (*block_num*)

Uploads a block body from AG

Parameters **data** – bytearray

`snap7.client.error_wrap` (*func*)

Parses a s7 error code returned the decorated function.

Snap7 server used for mimicking a siemens 7 server.

class `snap7.server.Server` (*log=True*)

A fake S7 server.

create ()

create the server.

destroy ()

destroy the server.

event_text (*event*)

Returns a textual explanation of a given event object

Parameters **event** – an PSrvEvent struct object

Returns the error string

get_mask (*kind*)

Reads the specified filter mask.

get_param (*number*)

Reads an internal Server object parameter.

get_status ()

Reads the server status, the Virtual CPU status and the number of the clients connected.

Returns server status, cpu status, client count

pick_event ()

Extracts an event (if available) from the Events queue.

`snap7.server.error_wrap` (*func*)

Parses a s7 error code returned the decorated function.

Snap7 code for partnering with a siemens 7 server.

This allows you to create a S7 peer to peer communication. Unlike the client-server model, where the client makes a request and the server replies to it, the peer to peer model sees two components with same rights, each of them can send data asynchronously. The only difference between them is the one who is requesting the connection.

class snap7.partner.**Partner** (*active=False*)

A snap7 partner.

as_b_send ()

Sends a data packet to the partner. This function is asynchronous, i.e. it terminates immediately, a completion method is needed to know when the transfer is complete.

b_recv ()

Receives a data packet from the partner. This function is synchronous, it waits until a packet is received or the timeout supplied expires.

b_send ()

Sends a data packet to the partner. This function is synchronous, i.e. it terminates when the transfer job (send+ack) is complete.

check_as_b_recv_completion ()

Checks if a packed received was received.

check_as_b_send_completion ()

Checks if the current asynchronous send job was completed and terminates immediately.

create (*active=False*)

Creates a Partner and returns its handle, which is the reference that you have to use every time you refer to that Partner.

Parameters *active* – 0

Returns a pointer to the partner object

destroy ()

Destroy a Partner of given handle. Before destruction the Partner is stopped, all clients disconnected and all shared memory blocks released.

get_last_error()

Returns the last job result.

get_param(*number*)

Reads an internal Partner object parameter.

get_stats()

Returns some statistics.

Returns a tuple containing bytes send, received, send errors, recv errors

get_status()

Returns the Partner status.

get_times()

Returns the last send and recv jobs execution time in milliseconds.

set_recv_callback()

Sets the user callback that the Partner object has to call when a data packet is incoming.

set_send_callback()

Sets the user callback that the Partner object has to call when the asynchronous data sent is complete.

stop()

Stops the Partner, disconnects gracefully the remote partner.

`snap7.partner.error_wrap(func)`

Parses a s7 error code returned the decorated function.

CHAPTER 7

Util

This module contains utility functions for working with PLC DB objects. There are functions to work with the raw bytearray data snap7 functions return. In order to work with this data you need to make python able to work with the PLC bytearray data.

For example code see test_util.py and example.py in the example folder.

example:

```
spec/DB layout

# Byte index    Variable name  Datatype
layout="""
4              ID              INT
6              NAME            STRING[6]

12.0           testbool1       BOOL
12.1           testbool2       BOOL
12.2           testbool3       BOOL
12.3           testbool4       BOOL
12.4           testbool5       BOOL
12.5           testbool6       BOOL
12.6           testbool7       BOOL
12.7           testbool8       BOOL
13             testReal        REAL
17             testDword       DWORD
"""

client = snap7.client.Client()
client.connect('192.168.200.24', 0, 3)

# this looks confusing but this means uploading from the PLC to YOU
# so downloading in the PC world :)

all_data = client.upload(db_number)
```

```
simple:

db1 = snap7.util.DB(
    db_number,          # the db we use
    all_data,           # bytearray from the plc
    layout,             # layout specification DB variable data
                        # A DB specification is the specification of a
                        # DB object in the PLC you can find it using
                        # the dataview option on a DB object in PCS7

    17+2,               # size of the specification 17 is start
                        # of last value
                        # which is a DWORD which is 2 bytes,

    1,                  # number of row's / specifications

    id_field='ID',      # field we can use to identify a row.
                        # default index is used
    layout_offset=4,     # sometimes specification does not start a 0
                        # like in our example
    db_offset=0          # At which point in 'all_data' should we start
                        # reading. if could be that the specification
                        # does not start at 0
)
```

Now we can use db1 in python as a dict. if 'ID' contains the 'test' we can identify the 'test' row in the all_data bytearray

To test if your layout matches the data from the plc you can just print db1[0] or db['test'] in the example

```
db1['test']['testbool1'] = 0
```

If we do not specify a id_field this should work to read out the same data.

```
db1[0]['testbool1']
```

to read and write a single Row from the plc. takes like 5ms!

```
db1['test'].write()
```

```
db1['test'].read()
```

```
class snap7.util.DB(db_number, _bytearray, specification, row_size, size, id_field=None, db_offset=0,
                    layout_offset=0, row_offset=0)
```

Manage a DB bytearray block given a specification of the Layout.

It is possible to have many repetitive instances of a specification this is called a “row”.

probably most usecases there is just one row

```
db1[0]['testbool1'] = test db1.write() # puts data in plc
```

```
class snap7.util.DB_Row(_bytearray, _specification, row_size=0, db_offset=0, layout_offset=0,
                       row_offset=0)
```

Provide ROW API for DB bytearray

```
export ()
```

export dictionary with values

get_bytearray()
return bytearray from self or DB parent

get_offset(*byte_index*)
Calculate correct beginning position for a row the `db_offset = row_size * index`

read(*client*)
read current data of db row from plc

write(*client*)
Write current data to db in plc

`snap7.util.get_bool(_bytearray, byte_index, bool_index)`
Get the boolean value from location in bytearray

`snap7.util.get_int(_bytearray, byte_index)`
Get int value from bytearray.

int are represented in two bytes

`snap7.util.get_real(_bytearray, byte_index)`
Get real value. create float from 4 bytes

`snap7.util.get_string(_bytearray, byte_index, max_size)`
parse string from bytearray

`snap7.util.parse_specification(db_specification)`
Create a db specification derived from a dataview of a db in which the byte layout is specified

`snap7.util.set_bool(_bytearray, byte_index, bool_index, value)`
Set boolean value on location in bytearray

`snap7.util.set_int(_bytearray, byte_index, _int)`
Set value in bytearray to int

`snap7.util.set_real(_bytearray, byte_index, real)`
Set Real value

make 4 byte data from real

`snap7.util.set_string(_bytearray, byte_index, value, max_size)`
Set string value

Params value string data

Params max_size max possible string size

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