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# **python-snap7 Documentation**

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## Introduction

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python-snap7 is a Python wrapper for the [Snap7 library](#). Snap7 is an open source, 32/64 bit, multi-platform Ethernet communication suite for interfacing natively with Siemens S7 PLCs.

Python-snap7 is developed for snap7 1.1.0 and Python2.7. It is tested on Windows (8.1 64 bit) and Linux, but it may work on other operating systems. Python 2.6 and Python 3+ may work, but are not fully tested yet.

The project development is centralized on [github](#).



## Installation

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here you can find out how to install python-snap7 on your system.

### 2.1 Snap7

To use python-snap7 you need to have the snap7 library installed.

#### 2.1.1 Ubuntu

If you are using Ubuntu you can use the Ubuntu packages from our [launchpad PPA](#). To install:

```
$ sudo add-apt-repository ppa:gijzelaar/snap7
$ sudo apt-get update
$ sudo apt-get install libsnap71 libsnap7-dev
```

#### 2.1.2 Windows

Download the zip file from the [sourceforge page](#). Unzip the zip file, and copy\* releaseWindows<Win64/Win32>snap7.dll\* somewhere in you system PATH, for example *C:WINDOWSsystem32*. Alternatively you can copy the file somewhere on your file system and adjust the system PATH.

#### 2.1.3 Compile from source

If you are not using Ubuntu or if you want to have more control you can download the latest source from [the sourceforge page](#) and do a manual compile. Download the file and run:

```
$ p7zip -d snap7-full-1.0.0.7z # requires the p7 program
$ cd build/<platform>          # where platform is unix or windows
$ make -f <arch>.mk              # where arch is your architecture, for example x86_64_linux
```

For more information about or help with compilation please check out the documentation on the [snap7 website](#).

### 2.2 snap7-python

python-snap7 is available on [PyPI](#). You can install it by using pip:

```
$ pip install python-snap7
```

You can also install it from the git repository or from a source tarball:

```
$ python ./setup.py install
```

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## development

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### 3.1 Github

We develop python-snap7 on [github](#). If you have any problems with python-snap7 please raise an issue in the [issue tracker](#). Even better is if you have a solution to problem! In that case you can make our live easier by following these steps:

- fork our repository on github
- Add a tests that will fail because of the problem
- Fix the problem
- Run the test suite again
- Commit to your repository
- Issue a github pullrequest.

Also we try to be as much pep8 compatible as possible, where possible and reasonable.

### 3.2 Test suite

python-snap7 comes with a test suite with 100% coverage. This test suite verifies that the code actually works and makes development much easier. To run all tests please run from the source:

```
$ ./run_tests.sh
```

Note that some tests require to run as root, since snap7 needs to bind on a privileged TCP port.

If the test complain about missing Python modules make sure the source directory is in your PYTHONPATH environment variable, or the python-snap7 module is installed.

### 3.3 Credits

python-snap7 is created by Gijs Molenaar and Stephan Preeker.

Special thanks to go to Davide Nardella for creating snap7, Thomas Hergenhahn for his libnodave and Thomas W for his S7comm wireshark plugin.



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## Client

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Snap7 client used for connection to a siemens7 server.

```
class snap7.client.Client
    A snap7 client

    ab_read(start, size)
        This is a lean function of Cli_ReadArea() to read PLC process outputs.

    ab_write(start, data)
        This is a lean function of Cli_WriteArea() to write PLC process outputs

    as_ab_read(start, size)
        This is the asynchronous counterpart of client.ab_read().

    as_ab_write(start, data)
        This is the asynchronous counterpart of Cli_ABWrite.

    as_ct_read()

    as_ct_write()

    as_db_fill()

    as_db_get(db_number)
        This is the asynchronous counterpart of Cli_DBGet.

    as_db_read(db_number, start, size)
        This is the asynchronous counterpart of Cli_DBRead.

        Returns user buffer.

    as_db_write(db_number, start, data)

    copy_ram_to_rom()

    create()
        create a SNAP7 client.

    db_get(db_number)
        Uploads a DB from AG.

    db_read(db_number, start, size)
        This is a lean function of Cli_ReadArea() to read PLC DB.

        Returns user buffer.

    destroy()
        destroy a client.
```

**full\_upload(\_type, block\_num)**

Uploads a full block body from AG. The whole block (including header and footer) is copied into the user buffer.

**Parameters** **block\_num** – Number of Block

**get\_block\_info(blocktype, db\_number)**

Returns the block information for the specified block.

**get\_connected()**

Returns the connection status

**Returns** a boolean that indicates if connected.

**get\_cpu\_info()**

Retrieves CPU info from client

**get\_cpu\_state()**

Retrieves CPU state from client

**get\_param(number)**

Reads an internal Client object parameter.

**get\_pdu\_length()**

Returns info about the PDU length.

**list\_blocks()**

Returns the AG blocks amount divided by type.

**Returns** a snap7.types.BlocksList object.

**list\_blocks\_of\_type(blocktype, size)**

This function returns the AG list of a specified block type.

**plc\_cold\_start()**

cold starts a client

**plc\_hot\_start()**

hot starts a client

**plc\_stop()**

stops a client

**read\_area(area, dbnumber, start, size)**

This is the main function to read data from a PLC. With it you can read DB, Inputs, Outputs, Merkers, Timers and Counters.

**Parameters**

- **dbnumber** – The DB number, only used when area= S7AreaDB
- **start** – offset to start writing
- **size** – number of units to read

**read\_multi\_vars(items)**

This function read multiple variables from the PLC.

**Parameters** **items** – list of S7DataItem objects

**Returns** a tuple with the return code and a list of data items

**set\_connection\_params(address, local\_tsap, remote\_tsap)**

Sets internally (IP, LocalTSAP, RemoteTSAP) Coordinates. This function must be called just before Cli\_Connect().

## Parameters

- **address** – PLC/Equipment IPV4 Address, for example “192.168.1.12”
- **local\_tsap** – Local TSAP (PC TSAP)
- **remote\_tsap** – Remote TSAP (PLC TSAP)

**set\_connection\_type** (*connection\_type*)

Sets the connection resource type, i.e the way in which the Clients connects to a PLC.

**Parameters** **connection\_type** – 1 for PG, 2 for OP, 3 to 10 for S7 Basic

**upload** (*block\_num*)

Uploads a block body from AG

**Parameters** **data** – bytarray

`snap7.client.error_wrap(func)`

Parses a s7 error code returned the decorated function.



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## Server

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Snap7 server used for mimicking a siemens 7 server.

**class** snap7.server.Server (*log=True*)

A fake S7 server.

**create()**

create the server.

**destroy()**

destroy the server.

**event\_text(event)**

Returns a textual explanation of a given event object

**Parameters** **event** – an PSrvEvent struct object

**Returns** the error string

**get\_mask(kind)**

Reads the specified filter mask.

**get\_param(number)**

Reads an internal Server object parameter.

**get\_status()**

Reads the server status, the Virtual CPU status and the number of the clients connected.

**Returns** server status, cpu status, client count

**pick\_event()**

Extracts an event (if available) from the Events queue.

**snap7.server.error\_wrap(func)**

Parses a s7 error code returned the decorated function.



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## Partner

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Snap7 code for partnering with a siemens 7 server.

This allows you to create a S7 peer to peer communication. Unlike the client-server model, where the client makes a request and the server replies to it, the peer to peer model sees two components with same rights, each of them can send data asynchronously. The only difference between them is the one who is requesting the connection.

**class** snap7.partner.**Partner** (*active=False*)

A snap7 partner.

**as\_b\_send()**

Sends a data packet to the partner. This function is asynchronous, i.e. it terminates immediately, a completion method is needed to know when the transfer is complete.

**b\_recv()**

Receives a data packet from the partner. This function is synchronous, it waits until a packet is received or the timeout supplied expires.

**b\_send()**

Sends a data packet to the partner. This function is synchronous, i.e. it terminates when the transfer job (send+ack) is complete.

**check\_as\_b\_recv\_completion()**

Checks if a packed received was received.

**check\_as\_b\_send\_completion()**

Checks if the current asynchronous send job was completed and terminates immediately.

**create** (*active=False*)

Creates a Partner and returns its handle, which is the reference that you have to use every time you refer to that Partner.

**Parameters active - 0**

**Returns** a pointer to the partner object

**destroy()**

Destroy a Partner of given handle. Before destruction the Partner is stopped, all clients disconnected and all shared memory blocks released.

**get\_last\_error()**

Returns the last job result.

**get\_param** (*number*)

Reads an internal Partner object parameter.

**get\_stats()**

Returns some statistics.

**Returns** a tuple containing bytes send, received, send errors, recv errors

**get\_status()**

Returns the Partner status.

**get\_times()**

Returns the last send and recv jobs execution time in milliseconds.

**set\_recv\_callback()**

Sets the user callback that the Partner object has to call when a data packet is incoming.

**set\_send\_callback()**

Sets the user callback that the Partner object has to call when the asynchronous data sent is complete.

**stop()**

Stops the Partner, disconnects gracefully the remote partner.

**snap7.partner.error\_wrap(func)**

Parses a s7 error code returned the decorated function.

**Util**

This module contains utility functions for working with PLC DB objects. There are functions to work with the raw bytarray data snap7 functions return In order to work with this data you need to make python able to work with the PLC bytarray data.

For example code see test\_util.py and example.py in the example folder.

example:

```
spec/DB layout

# Byte index      Variable name   Datatype
layout=""""
4              ID             INT
6              NAME           STRING[6]

12.0            testbool1     BOOL
12.1            testbool2     BOOL
12.2            testbool3     BOOL
12.3            testbool4     BOOL
12.4            testbool5     BOOL
12.5            testbool6     BOOL
12.6            testbool7     BOOL
12.7            testbool8     BOOL
13              testReal      REAL
17              testDword    DWORD
"""

client = snap7.client.Client()
client.connect('192.168.200.24', 0, 3)

# this looks confusing but this means uploading from the PLC to YOU
# so downloading in the PC world :)

all_data = client.upload(db_number)

simple:

db1 = snap7.util.DB(
    db_number,          # the db we use
    all_data,           # bytearray from the plc
    layout,             # layout specification DB variable data
    # A DB specification is the specification of a
    # DB object in the PLC you can find it using
```

```

        # the dataview option on a DB object in PCS7

17+2,           # size of the specification 17 is start
                # of last value
                # which is a DWORD which is 2 bytes,
                # number of row's / specifications
id_field='ID',    # field we can use to identify a row.
                    # default index is used
layout_offset=4,   # sometimes specification does not start a 0
                    # like in our example
db_offset=0        # At which point in 'all_data' should we start
                    # reading. if could be that the specification
                    # does not start at 0
)

```

Now we can use db1 in python as a dict. if 'ID' contains  
the 'test' we can identify the 'test' row in the all\_data bytarray

To test of you layout matches the data from the plc you can  
just print db1[0] or db['test'] in the example

```
db1['test']['testbool1'] = 0
```

If we do not specify a id\_field this should work to read out the  
same data.

```
db1[0]['testbool1']
```

to read and write a single Row from the plc. takes like 5ms!

```
db1['test'].write()
```

```
db1['test'].read()
```

```
class snap7.util.DB(db_number, _bytarray, specification, row_size, size, id_field=None, db_offset=0,  
                   layout_offset=0, row_offset=0)
```

Manage a DB bytarray block given a specification of the Layout.

It is possible to have many repetitive instances of a specification this is called a “row”.

probably most usecases there is just one row

```
db1[0]['testbool1'] = test db1.write() # puts data in plc
```

```
class snap7.util.DB_Row(_bytarray, _specification, row_size=0, db_offset=0, layout_offset=0,  
                      row_offset=0)
```

Provide ROW API for DB bytarray

```
export()
```

export dictionary with values

```
get_bytarray()
```

return bytarray from self or DB parent

```
get_offset(byte_index)
```

Calculate correct beginning position for a row the db\_offset = row\_size \* index

```
read(client)
```

read current data of db row from plc

```
write(client)
    Write current data to db in plc

snap7.util.get_bool(_bytarray, byte_index, bool_index)
    Get the boolean value from location in bytarray

snap7.util.get_int(_bytarray, byte_index)
    Get int value from bytarray.

    int are represented in two bytes

snap7.util.get_real(_bytarray, byte_index)
    Get real value. create float from 4 bytes

snap7.util.get_string(_bytarray, byte_index, max_size)
    parse string from bytarray

snap7.util.parse_specification(db_specification)
    Create a db specification derived from a dataview of a db in which the byte layout is specified

snap7.util.set_bool(_bytarray, byte_index, bool_index, value)
    Set boolean value on location in bytarray

snap7.util.set_int(_bytarray, byte_index, _int)
    Set value in bytarray to int

snap7.util.set_real(_bytarray, byte_index, real)
    Set Real value

    make 4 byte data from real

snap7.util.set_string(_bytarray, byte_index, value, max_size)
    Set string value

    Params value string data

    Params max_size max possible string size
```



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